





HOW IT ALL STARTED

The Robot Operating System (ROS) project was created in 2007 at Stanford AI Lab as an attempt to solve the major problems of robotics engineering.



- Diverse nature of robots (multidisciplinary competence required).
- Re-inventing the wheel (too much time and effort for things already done).



In 2009, the first distribution of ROS was released: ROS 0.4

Around 2015, the ROS 2 project started by the OSRF to overcome the deficiencies of ROS for commercial products.



